Estimation of low-energy refolding paths Visualization of Lattice Protein Dynamics

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Outline

- 1 Lattice Proteins
- 2 Conformation space
- 3 Energy landscapes
- 4 Refolding paths
- 5 Dynamics
- 6 Visualization

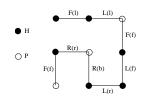


The HP-model

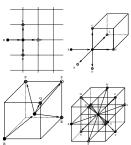
Suggested by Dill, Chan and Lau in the late 1980ies. In this *simplified model*, a conformation is a *self-avoiding walk (SAW)* on a given lattice in 2 or 3 dimensions. Each bond is a straight line, bond angles have a few discrete values. The 20 letter alphabet of amino acids (monomers) is reduced to a two letter alphabet, namely **H** and **P**. H represents hydrophobic monomers, P represents hydrophilic or *polar* monomers.

Advantages:

- lattice-independent folding algorithms
- simple energy function
- hydrophobicity can be reasonably modeled



FRRLLFLF





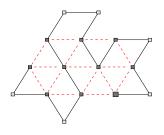
Contact Potentials

Generally, the energy function for a sequence with n residues $\mathfrak{S} = \mathfrak{s}_1\mathfrak{s}_2\dots\mathfrak{s}_n$ with $\mathfrak{s}_i \in \mathscr{A} = \{a_1, a_2, \dots, a_b\}$, the alphabet of b residues, and an overall configuration $x = (\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n)$ on a lattice \mathscr{L} can be written as the sum of pair potentials

$$E(\mathfrak{S}, x) = \sum_{\substack{i < j-1 \\ |\mathbf{x}_i - \mathbf{x}_j| = 1}} \Psi[\mathfrak{s}_i, \mathfrak{s}_j].$$

Lattice proteins

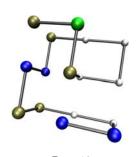
 $\mathfrak{S}=$ НРНРНННРРНННРНРН n=16



$$E=-15$$

$$\begin{array}{cccc} & H & P \\ H & -1 & 0 \\ P & 0 & 0 \end{array}$$

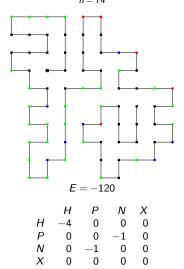
 $\mathfrak{S} = \mathtt{NNHHPPNNPHHHHPXP} \quad n = 16$



E = -16

	Η	Ρ	Ν	Χ
Η	-4	0	0	0
Ρ	0	1	-1	0
Ν	0	-1	1	0
Χ	0	0	0	0

Lattice proteins - interaction scheme II



tbi

Folding landscape - energy landscape

The energy landscape of a biopolymer molecule is a complex surface of the (free) energy versus the conformational degrees of freedom.

Number of lattice protein structures

$$c_n \sim \mu^n \cdot n^{\gamma-1}$$
 problem is NP-hard

In the RNA case $c_n \sim 1.86^n \cdot n^{-\frac{3}{2}}$

dynamic programming algorithms available

dim	Lattice Type	μ	γ
2	SQ	2.63820	1.34275
	TRI	4.15076	1.343
	HEX	1.84777	1.345
3	SC	4.68391	1.161
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Formally, three things are needed to construct an energy landscape:

- A set X of configurations
- \blacksquare a symmetric neighborhood relation $\mathfrak{N}: X \times X$
- an energy function $f: X \to \mathbb{R}$



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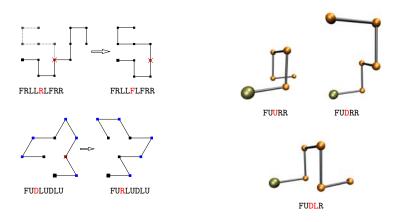
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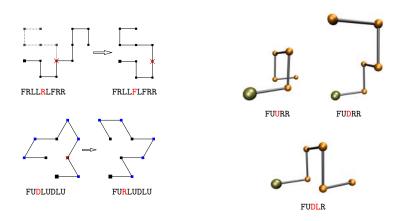
The move set



- For each move there must be an inverse move
- Resulting structure must be in X
- Move set must be *ergodic*



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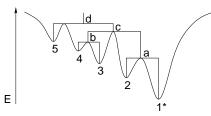
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Some topological definitions:

A structure is a

- local minimum if its energy is lower than the energy of all neighbors
- local maximum if its energy is higher than the energy of all neighbors
- saddle point if there are at least two local minima that can be reached by a downhill walk starting at this point



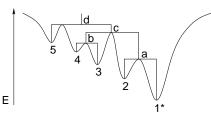
- **a** walk between two conformations x and y as a list of conformations $x = x_1 \dots x_{m+1} = y$ such that $\forall 1 \leq i \leq m : \mathfrak{N}(x_i, x_{i+1})$
- the lower part of the energy landscape (written as $X^{\leq \eta}$) as all conformations x such that $E(\mathfrak{S},x) \leq \eta$ (with a predefined threshold
 - C. Flamm, I. L. Hofacker, P. F. Stadler, and M. T. Wolfinge Barrier trees of degenerate landscapes. *Z. Phys. Chem.*, 216:155–173, 2002.



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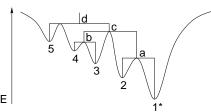
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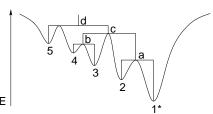




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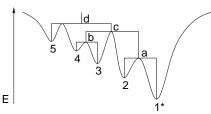
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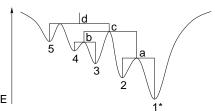




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We further define

- **a** walk between two conformations x and y as a list of conformations $x = x_1 \dots x_{m+1} = y$ such that $\forall 1 \le i \le m : \mathfrak{N}(x_i, x_{i+1})$
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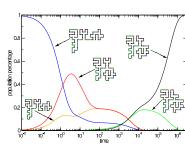
C. Flamm, I. L. Hofacker, P. F. Stadler, and M. T. Wolfinger. Barrier trees of degenerate landscapes. *Z. Phys. Chem.*, 216:155–173, 2002.



Information from the barrier tree

- Local minima
- Saddle points
- Barrier heights
- Gradient basins
- Partition functions and free energies of (gradient) basins

This information can be used to approximate the dynamics of biopolymers, i.e. transition rates between different macrostates (basins in the barrier tree)



The lower part of the energy landscape

Two conformations x and y are mutually accessible at the level η (written as $x \leftrightarrow \frac{\eta}{2} \hookrightarrow y$) if there is a walk from x to y such that all conformations z in the walk satisfy $E(\mathfrak{S},z) \leq \eta$. The saddle height $\hat{f}(x,y)$ of x and y is defined by

$$\hat{f}(x,y) = \min\{\eta \mid x \leftrightarrow \underline{\eta} \hookrightarrow y\}$$

Given the set of all local minima $X_{\min}^{\leq \eta}$ below threshold η , the lower energy part $X^{\leq \eta}$ of the energy landscape can alternatively be written as

$$X^{\leq \eta} = \{ y \mid \exists x \in X_{\min}^{\leq \eta} : \hat{f}(x, y) \leq \eta \}$$

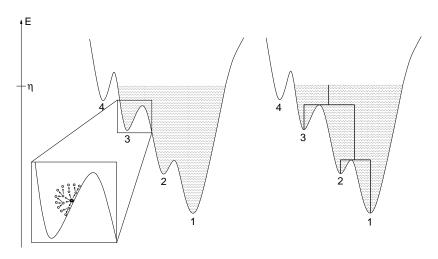
Given a restricted set of low-energy conformations, X_{init} , and a reasonable value for η , the lower part of the energy landscape can be calculated.



M. T. Wolfinger, S. Will, I. L. Hofacker, R. Backofen, and P. F. Stadler. Exploring the lower part of discrete polymer model energy landscapes. *Europhys. Lett.*, 2006.

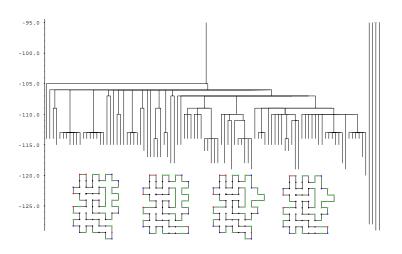


The Flooder approach



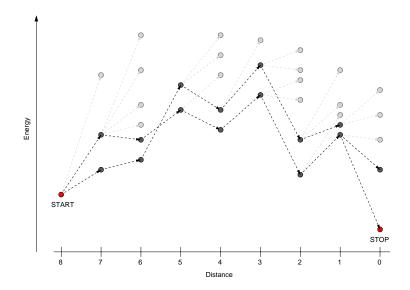


!Connected



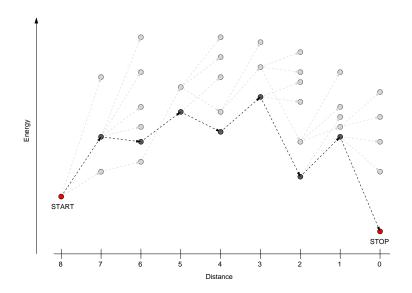


PathFinder - illustration



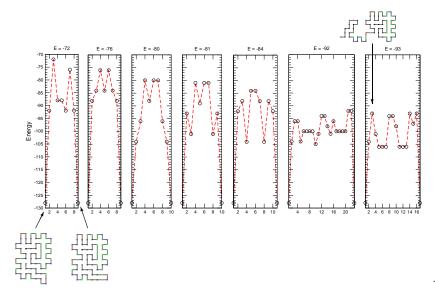


PathFinder - illustration

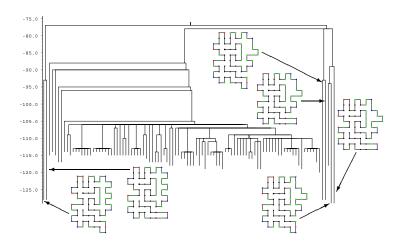




Refolding profiles



Connected!



Dynamics of biopolymers

The probability distribution P of structures as a function of time is ruled by a set of forward equations, also known as the master equation

$$rac{dP_t(x)}{dt} = \sum_{y
eq x} [P_t(y)k_{xy} - P_t(x)k_{yx}]$$

Given an initial population distribution, how does the system evolve in time? (What is the population distribution after n time-steps?)

$$\frac{d}{dt}P_t = \mathbf{U}P_t \implies P_t = e^{t\mathbf{U}}P_0$$



Barrier tree kinetics

For a reduced description we need

- macro-states that form a partition of full configuration space
- transition rates between macro-states, e.g.

$$\begin{split} r_{\beta\alpha} &= \Gamma_{\beta\alpha} \exp\left(-(E_{\beta\alpha}^* - G_\alpha)/kT\right) \quad \text{or} \\ r_{\beta\alpha} &= \sum_{y \in \beta} \sum_{x \in \alpha} r_{yx} \text{Prob}[x|\alpha] \quad \text{for } \alpha \neq \beta \text{ with } r_{yx} = \left\{ \begin{array}{ll} e^{\frac{-\Delta E}{kT}} & \text{if } \Delta E > 0 \\ 0 & y \notin \mathcal{N}(x) \\ 1 & \end{array} \right. \end{split}$$

All relevant quantities can be computed via the flooding algorithm.

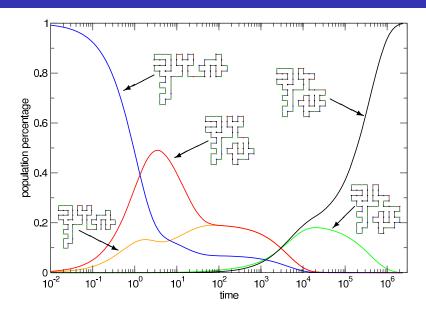


M. T. Wolfinger, W. A. Svrcek-Seiler, C. Flamm, I. L. Hofacker, and P. F. Stadler. Efficient computation of RNA folding dynamics.

J. Phys. A: Math. Gen., 37(17):4731-4741, 2004.



Barrier tree kinetics - example





Kinetic Folding Algorithm

Simulate folding kinetics by a rejection-less Monte-Carlo type algorithm:

Generate all neighbors using the move-set

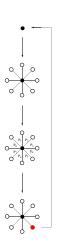
Assign rates to each move, e.g.

$$P_i = \min \left\{ 1, \exp \left(-rac{\Delta E}{kT}
ight)
ight\}$$

Select a move with probability proportional to its rate Advance clock $1/\sum_i P_i$.



C. Flamm, W. Fontana, I. Hofacker, and P. Schuster. RNA folding kinetics at elementary step resolution. *RNA*, 6:325–338, 2000.





Visualization

- Visualize Pinfold outputSupport data analysis
- Emphasize possible relationships
- Provide simulation comparison
- Provide data analysis and exploration
- Uncover regularitiesExpose the unseen
- Speed up coginition

- Start with an overview
- Let the user filter out interesting data
- Show details only on demand for different data





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Shneiderman's mantra:

"Overview first, zoom and filter, details on demand"

- Start with an overview
- Let the user filter out interesting data
- Show details only on demand for different data



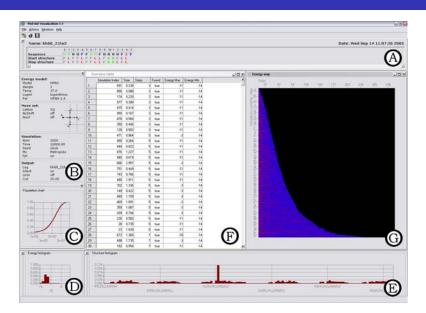
S. Pötzsch, G. Scheuermann, M. T. Wolfinger, C. Flamm, and P. F. Stadler.

Visualization of lattice-based protein folding simulations.

In 10th International Conference on Information Visualization (IV06), 2006.



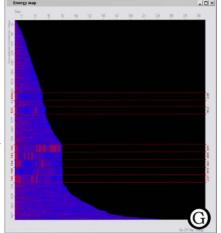
Overview first



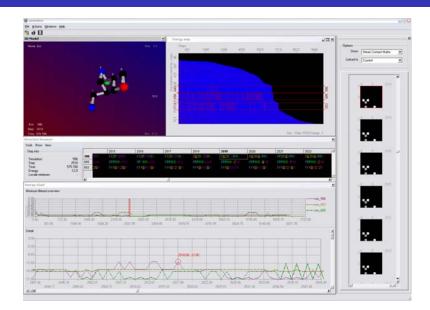


Zoom and filter

- Energy map
- Focus & context technique
- Huge data sets, limited screen size
- Details and overview in one window



Details on demand



- Barrier trees approximate the landscape topology and folding kinetics.
- A heuristic approach allows to sample low-energy refolding paths between different structures
- A macrostate approach of folding kinetics reduces simulation time drastically.
- A tool for visualization of folding trajectories enables a thorough investigation of folding kinetics simulations.
- This newly generated framework provides a powerful method for further refinement of biopolymer folding landscapes.



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